

CPSC 340: Machine Learning and Data Mining

More CNNs
and
Deep Learning Software

Admin

- **Assignment 6:**
 - Due Thursday
- **Final exam:**
 - Saturday April 14, 3:30pm-6:00pm, SUB 2201
 - Covers Assignments 1-6, Lectures 2-31 (**not** today or Friday)

AlexNet Convolutional Neural Network

- ImageNet 2012 won by **AlexNet**:
 - 15.4% error vs. 26.2% for closest competitor.
 - 5 convolutional layers.
 - 3 fully-connected layers.
 - SG with momentum.
 - ReLU non-linear functions.
 - Data translation/reflection/cropping.
 - L2-regularization + Dropout.
 - 5-6 days on two GPUs.

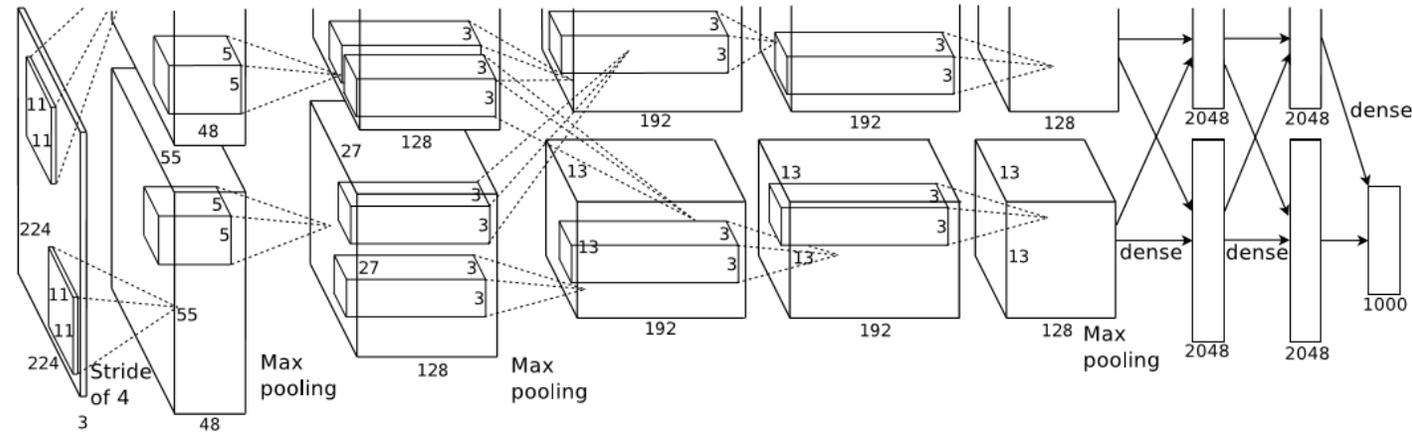


Figure 2: An illustration of the architecture of our CNN, explicitly showing the delineation of responsibilities between the two GPUs. One GPU runs the layer-parts at the top of the figure while the other runs the layer-parts at the bottom. The GPUs communicate only at certain layers. The network's input is 150,528-dimensional, and the number of neurons in the network's remaining layers is given by 253,440–186,624–64,896–64,896–43,264–4096–4096–1000.

AlexNet Convolutional Neural Network

- ImageNet 2012 won by AlexNet:
 - 15.4% error vs. 26.2% for closest competitor.

*Gaussian times sine/cosine:
"Gabor" filters*

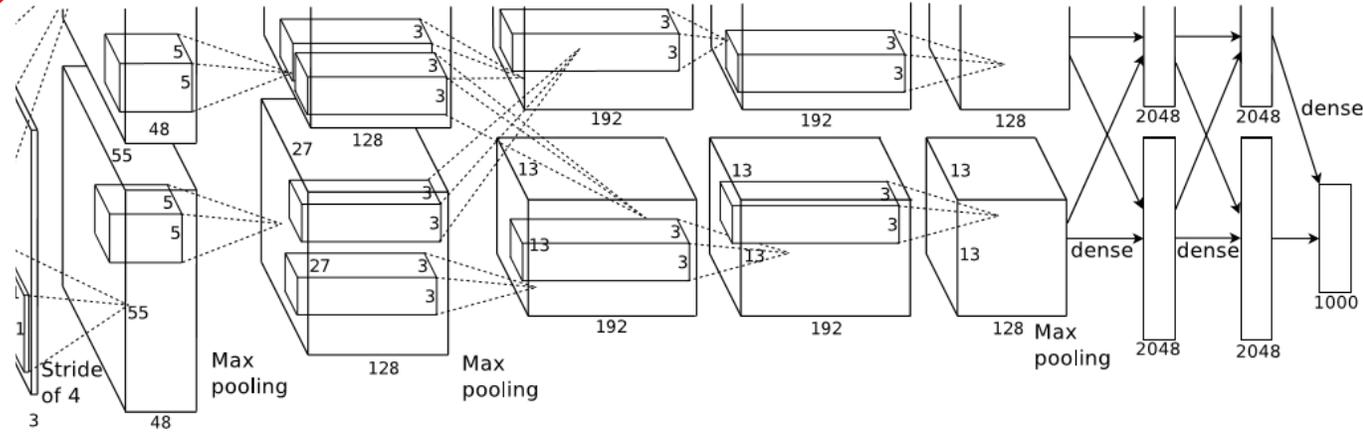


Figure 3: 96 convolutional kernels of size $11 \times 11 \times 3$ learned by the first convolutional layer on the $224 \times 224 \times 3$ input images. The

Figure 2: An illustration of the architecture of our CNN, explicitly showing the delineation of responsibilities between the two GPUs. One GPU runs the layer-parts at the top of the figure while the other runs the layer-parts at the bottom. The GPUs communicate only at certain layers. The network's input is 150,528-dimensional, and number of neurons in the network's remaining layers is given by 253,440–186,624–64,896–64,896–43,264–6–4096–1000.

Bonus slides: other well-known networks

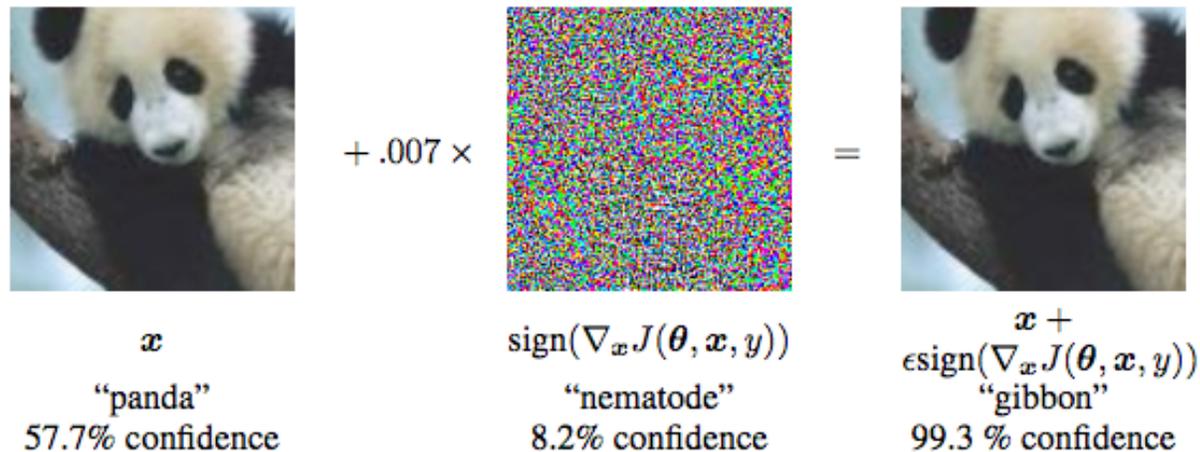
- ZFNet (2013)
 - “deconvolutional networks” to see what CNNs learn
- VGGNet (2014)
 - Small (3x3) convolutions, many (19) layers
- GoogLeNet (2014)
 - 22 layers, no fully connected layers
 - Try to predict labels at multiple locations
- ResNet (2015) – we saw this last class
 - Learn “residuals” between input and desired signal
- DenseNet (2016)
 - Layer layers see values in early layers

Mission Accomplished?

- For speech recognition and object detection:
 - No other methods have ever given the current level of performance.
 - Deep models continue to improve performance on these and related tasks.
 - We don't know how to scale up other universal approximators.
 - There is likely some overfitting to popular datasets like ImageNet.
- CNNs are now making their way into products.
 - Apple face recognition.
 - Amazon Go
 - Self-driving cars.

Mission Accomplished?

- Despite high-level of abstraction, deep CNNs are easily fooled:
 - But progress on fixing ‘blind spots’.
- Recent work: imperceptible noise that changes the predicted label



- Can someone repaint a stop sign and fool self-driving cars?

Beyond Classification (CPSC 540)

- “Fully convolutional” neural networks allow “dense” prediction:

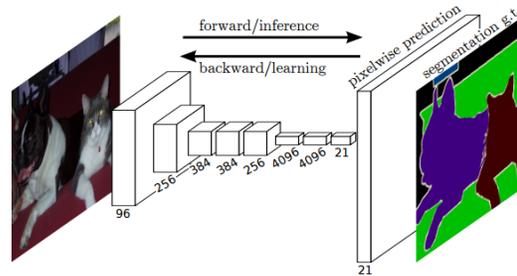


Figure 1. Fully convolutional networks can efficiently learn to make dense predictions for per-pixel tasks like semantic segmentation.

- Image segmentation:

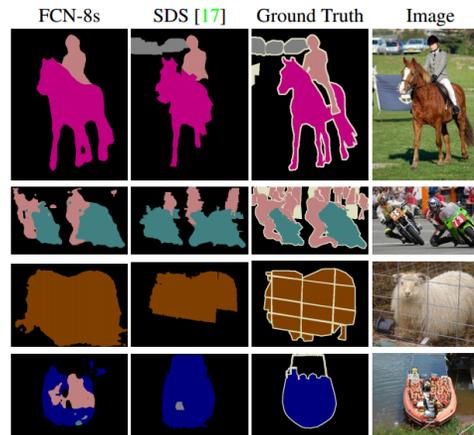


Figure 6. Fully convolutional segmentation nets produce state-of-the-art performance on PASCAL. The left column shows the output of our highest performing net, FCN-8s. The second shows the segmentations produced by the previous state-of-the-art system by Hariharan *et al.* [17]. Notice the fine structures recovered (first

Beyond Classification (CPSC 540)

- “Fully convolutional” neural networks allow “dense” prediction:

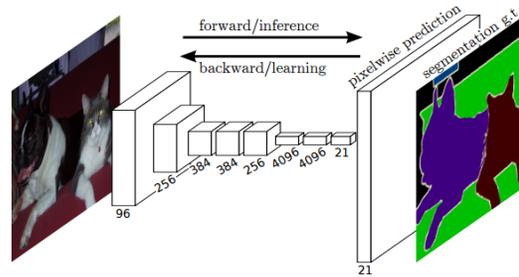
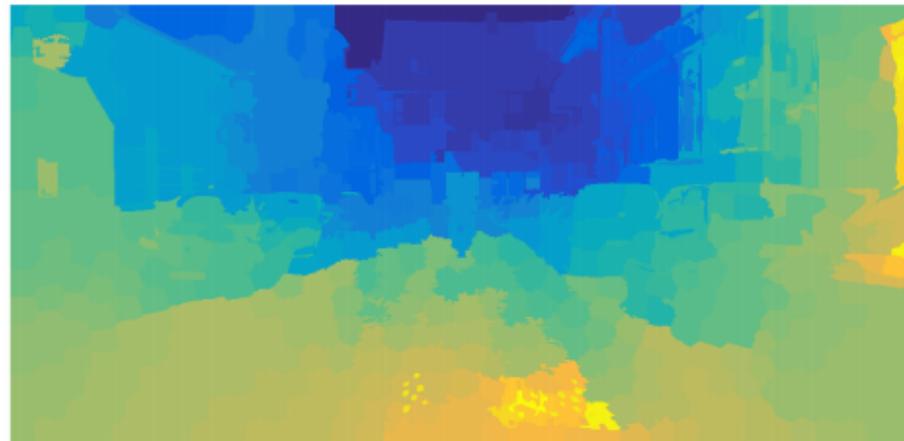


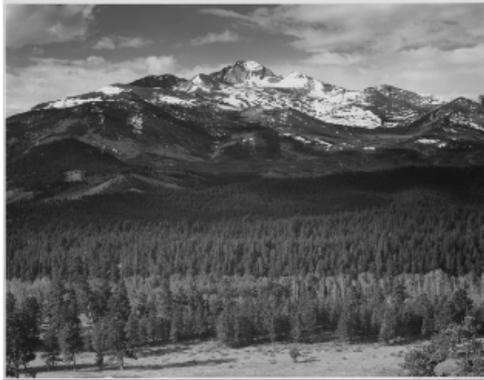
Figure 1. Fully convolutional networks can efficiently learn to make dense predictions for per-pixel tasks like semantic segmentation.

- Depth Estimation:



Beyond Classification

- Image **colorization**:



Colorado National Park, 1941



Textile Mill, June 1937



Berry Field, June 1909



Hamilton, 1936

– [Image Gallery](#), [Video](#)

Inceptionism

- A crazy idea:
 - Instead of weights, use backpropagation to take **gradient with respect to x_i** .
- **Inceptionism** with trained network:
 - Fix the label y_i (e.g., “banana”).
 - Start with random noise image x_i .
 - Use **gradient descent on image x_i** .
 - Add a spatial regularizer on x_{ij} :
 - Encourages neighbouring x_{ij} to be similar.

“Show what you think a banana looks like.”



optimize
with prior



Inceptionism

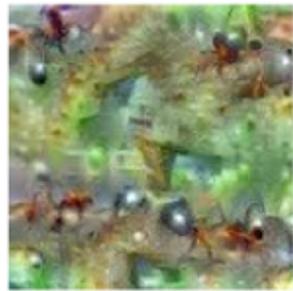
- Inceptionism for different class labels:



Hartebeest



Measuring Cup



Ant



Starfish



Anemone Fish



Banana

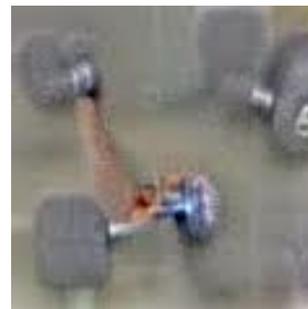


Parachute



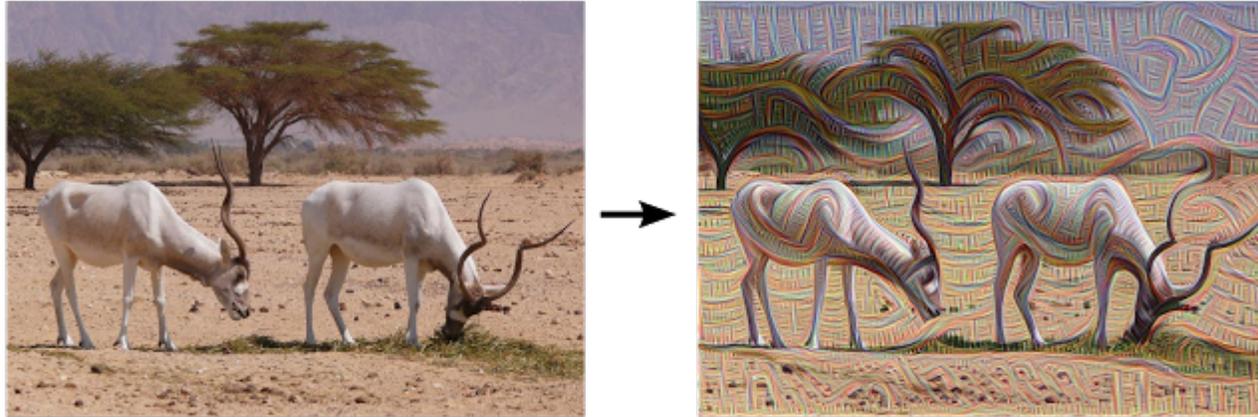
Screw

Dumbbell



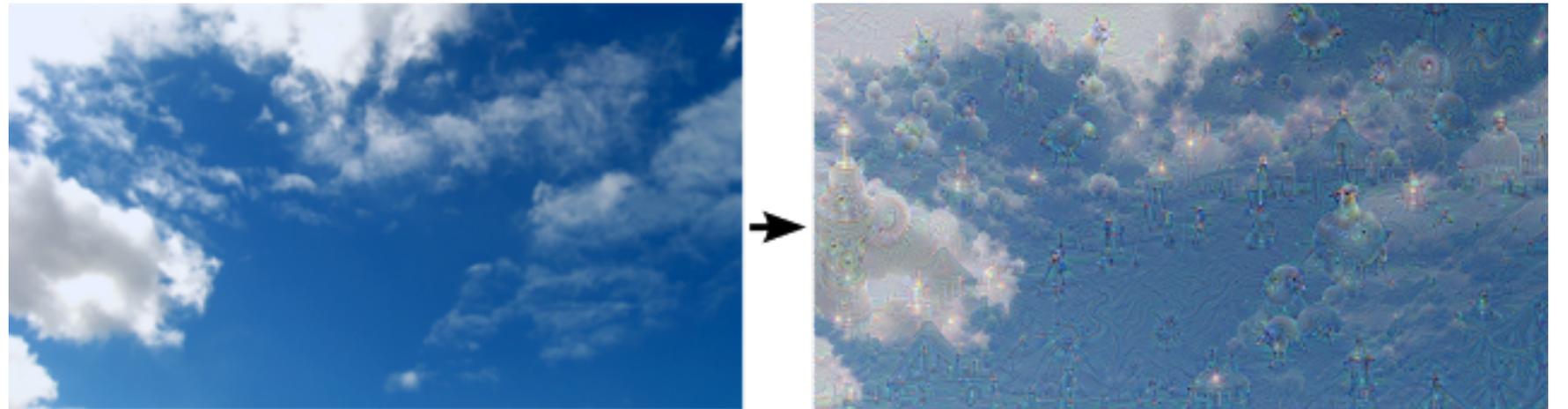
Inceptionism

- **Inceptionism** where we try to match $z_i^{(m)}$ values instead of y_i .
 - Shallow 'm':



Inceptionism

- **Inceptionism** where we try to match $z_i^{(m)}$ values instead of y_i .
 - Deepest 'm':



"Admiral Dog!"



"The Pig-Snail"



"The Camel-Bird"



"The Dog-Fish"

Inceptionism

- **Inceptionism** where we try to match $z_i^{(m)}$ values instead of y_i .
 - “Deep dream” starts from random noise:



- [Inceptionism gallery](#)
- [Deep Dream video](#)

Artistic Style Transfer

- Artistic style transfer:
 - Given a content image 'C' and a style image 'S'.
 - Make a image that has content of 'C' and style of 'S'.

Content:



Style:



Artistic Style Transfer



Examples



Figure: **Left:** My friend Grant, **Right:** Grant as a pizza

Artistic Style Transfer

- Recent methods combine CNNs with graphical models (CPSC 540):



Input A



Input B



Content A + Style B



Content B + Style A

Artistic Style Transfer

- Recent methods combine CNNs with graphical models (CPSC 540):



Input style



Input content



Ours

Artistic Style Transfer for Video

- Combining style transfer with optical flow:
 - <https://www.youtube.com/watch?v=Khuj4ASldmU>
- Videos from a former CPSC 340 student/TA's paper:



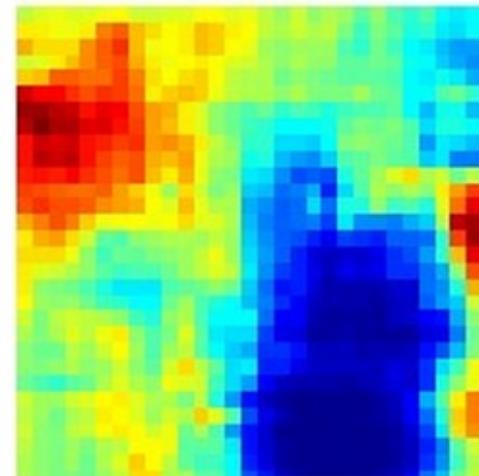
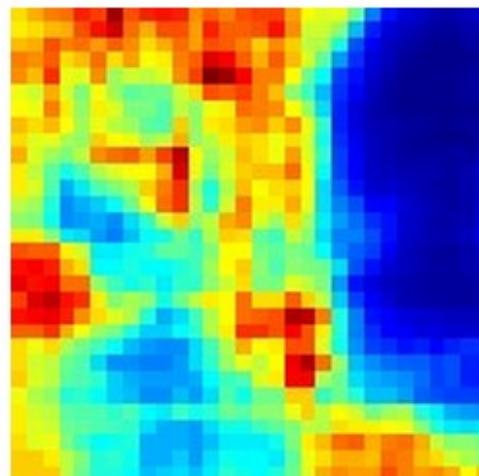
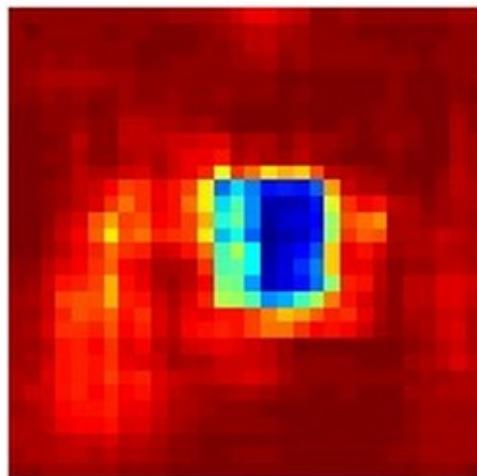
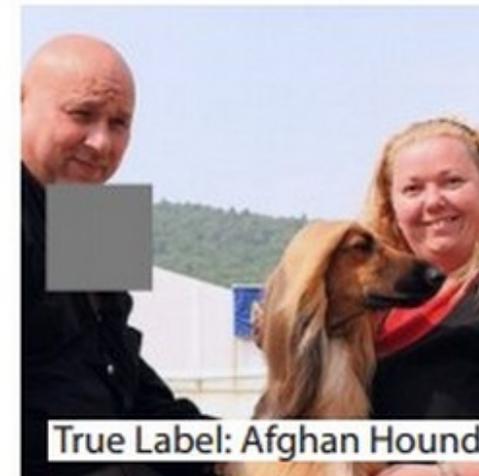
Move to Jupyter for deep learning software

Summary

- Convnets can do a lot of **cool stuff**
- You can train models on **GPUs in the cloud** with minimal hassle

ZFNet Convolutional Neural Network

- Looked at how prediction changes if we hide part of the image:



ZFNet Convolutional Neural Network

- ImageNet 2013 won by variation of AlexNet called ZF Net:
 - 11.2% error (now using 7x7 stride 2 instead of 11x11 stride 4).
 - Introduced **deconvolutional networks** to visualize what CNNs learn.

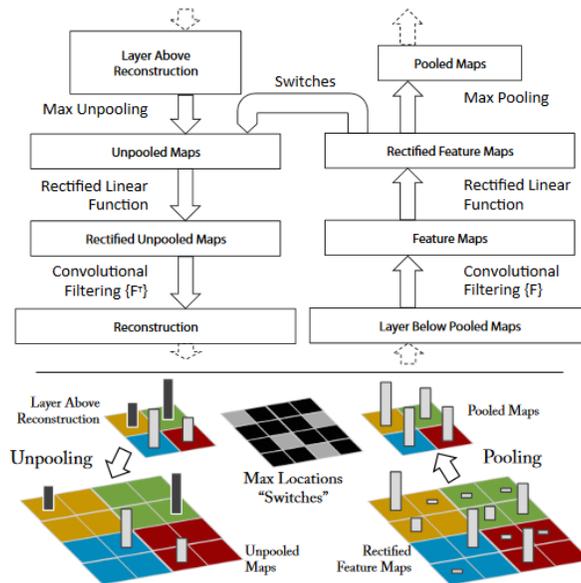
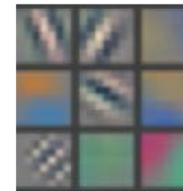
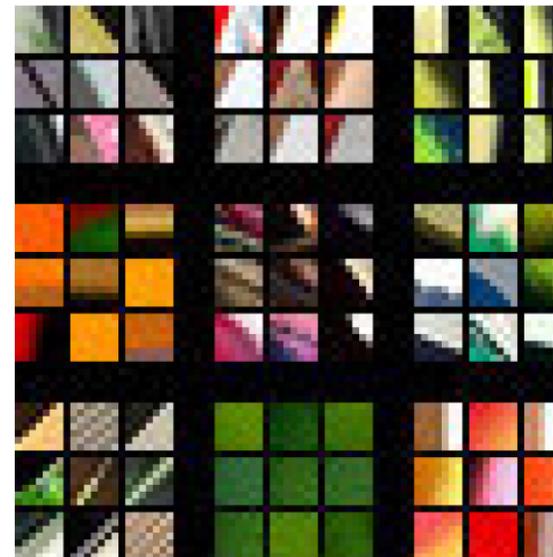


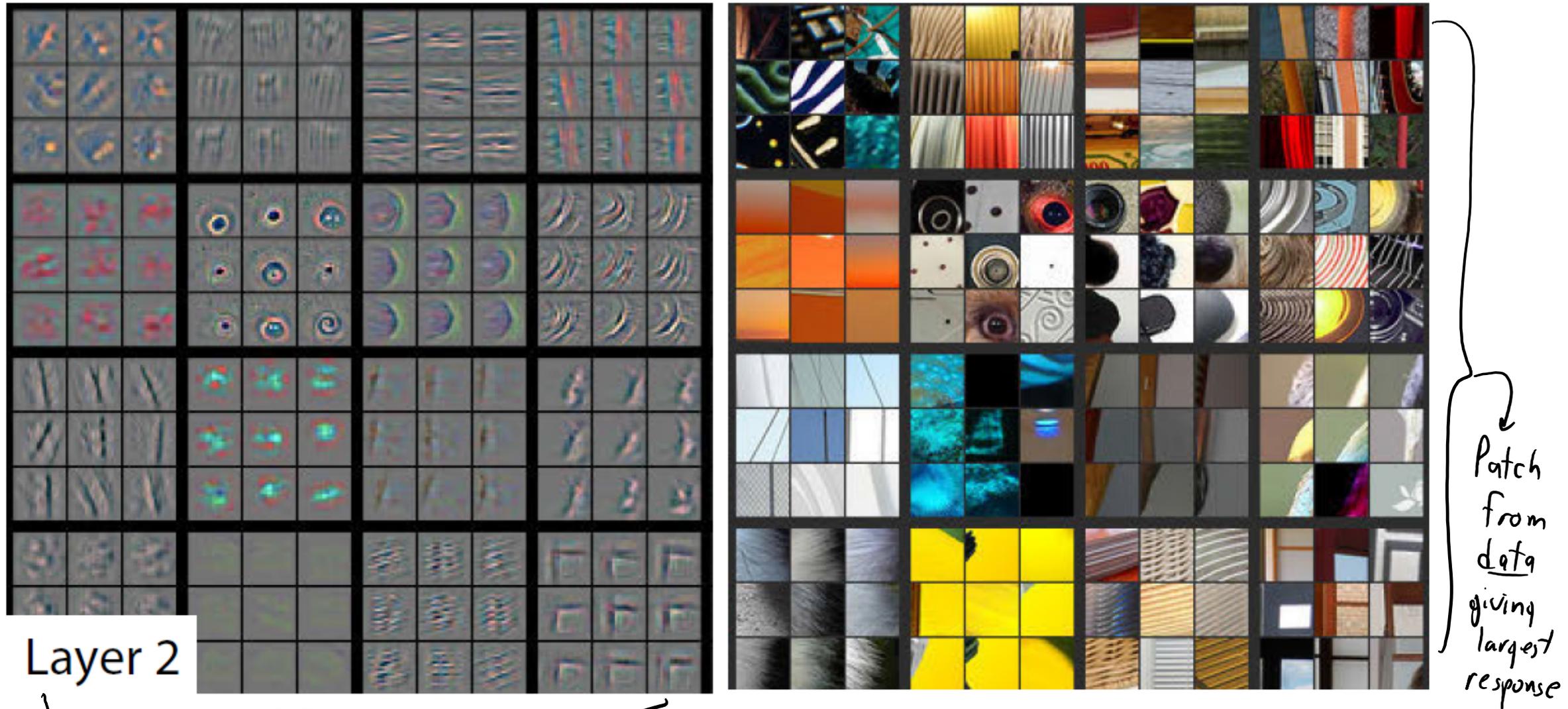
Figure 1. Top: A deconvnet layer (left) attached to a convnet layer (right). The deconvnet will reconstruct an approximate version of the convnet features from the layer beneath. Bottom: An illustration of the unpooling operation in the deconvnet, using *switches* which record the location of the local max in each pooling region (colored zones) during pooling in the convnet.



Layer 1



ZFNet Convolutional Neural Network

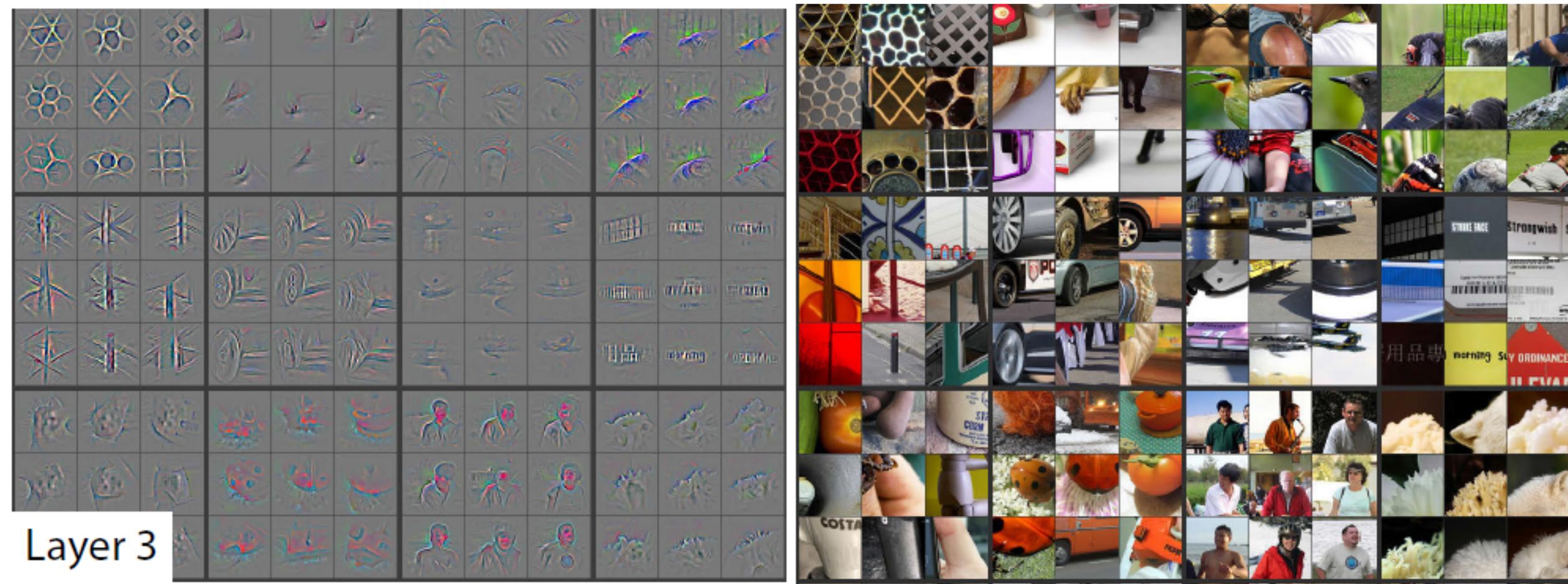


Layer 2

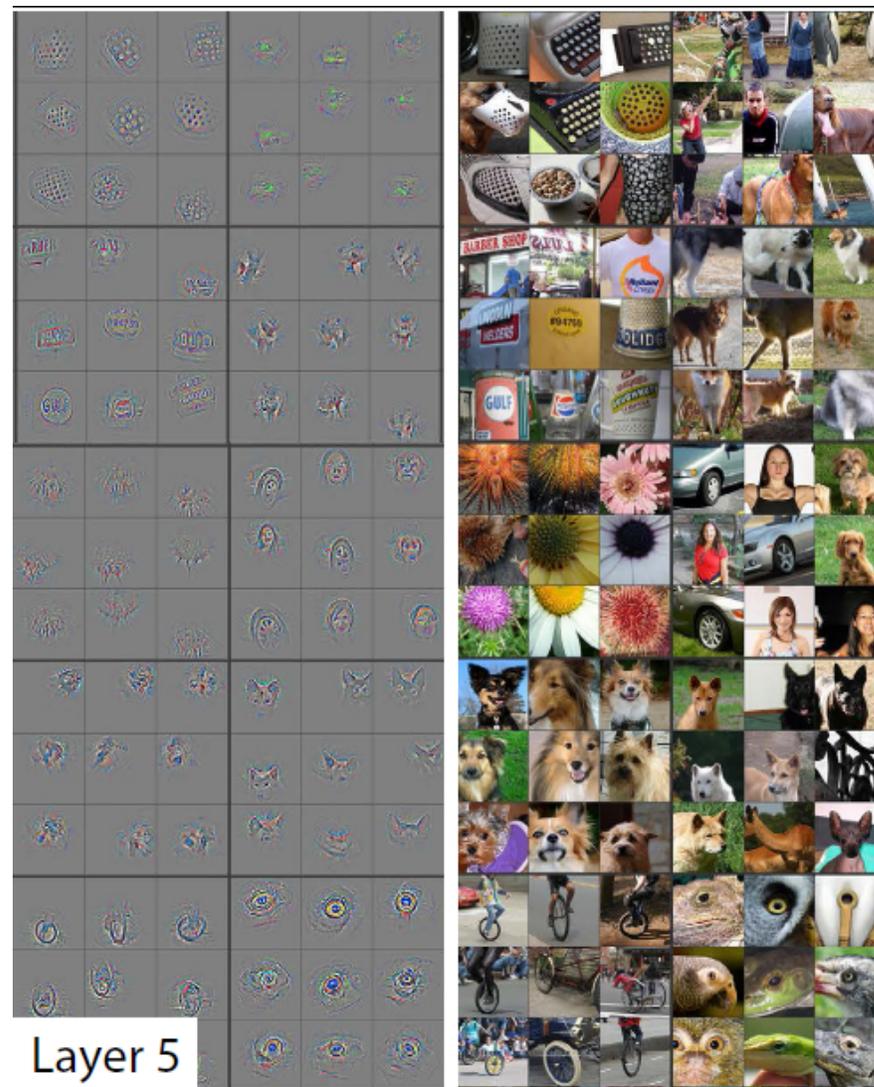
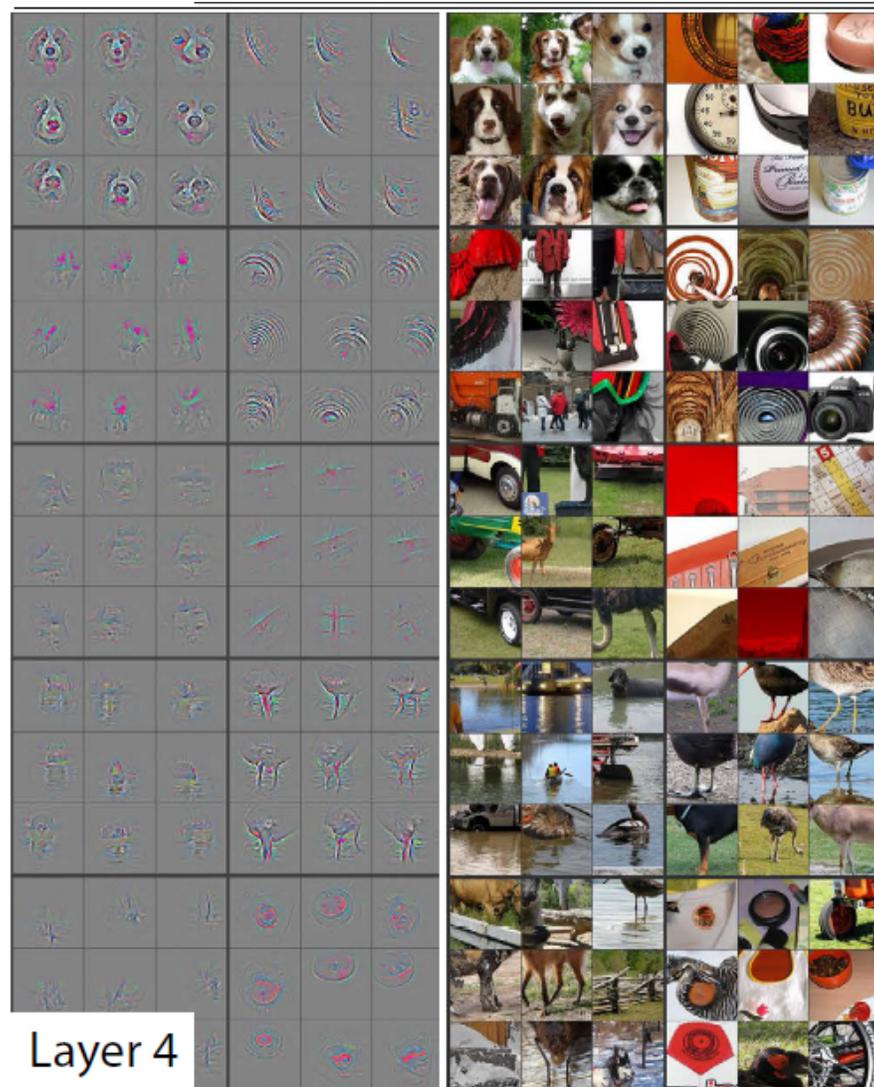
Patch from data giving largest response

→ Deconvolution network giving patch that leads to largest response

ZFNet Convolutional Neural Network

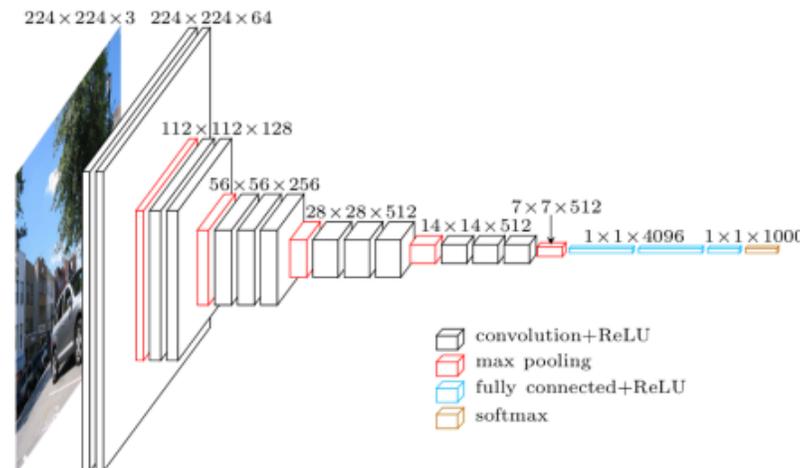


ZFNet Convolutional Neural Network



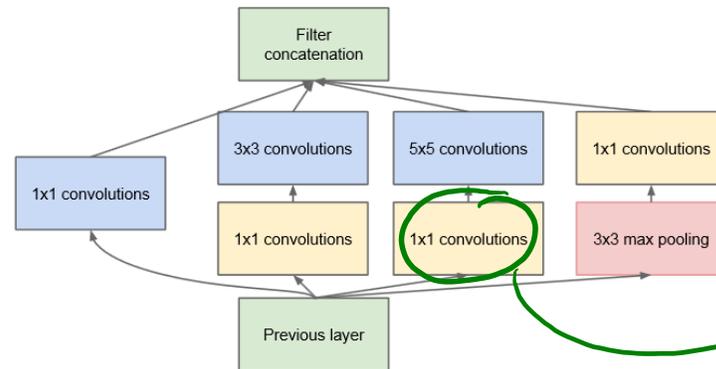
VGG Convolutional Neural Network

- Image 2014 “Localization” Task won by a **19-layer VGG** network:
 - 7.3% error for classification (2nd place).
 - Uses **3x3 convolution layers** with stride of 1:
 - 3x3 followed by 3x3 simulates a 5x5, and another 3x3 simulates a 7x7, and so on.
 - Speeds things up and reduces number of parameters.
 - Increases number of non-linear ReLU operations.
 - “Deep and simple”: variants of VGG are among the most popular CNNs.



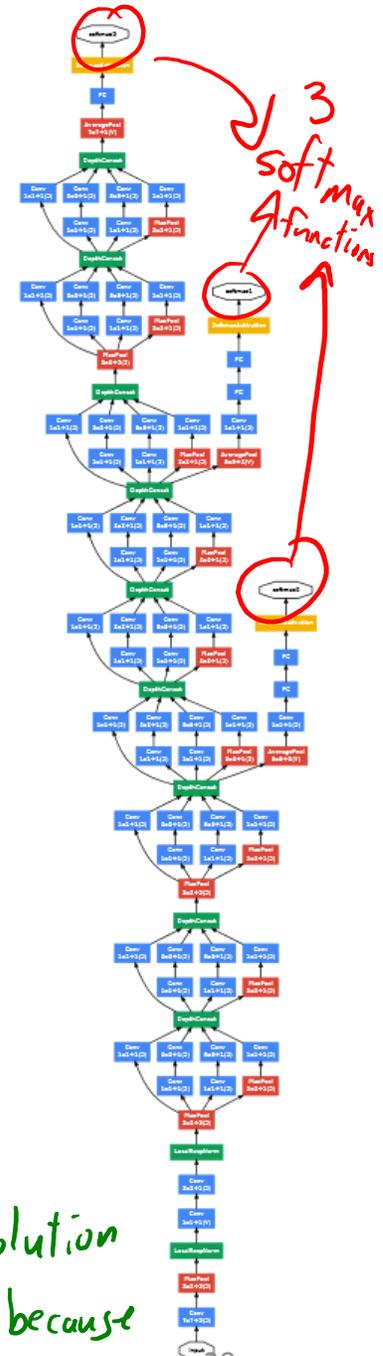
GoogLeNet

- Image 2014 classification task won by **GoogLeNet**:
 - 6.7% errors.
 - 22 layers
 - **No fully connected** layers.
 - During training, try to predict **label at multiple locations**.
 - During testing, just take the deepest predictions.
 - “**Inception**” modules: combine convolutions of different sizes.



(b) Inception module with dimensionality reduction

"1x1" convolution makes sense because these are first 2 dimensions of 3D conv.



ResNet

- Image 2015 won by **Resnet** (all 5 tasks):
 - 3.6% error (below estimate 5% human error).
 - 152 layers (2-3 weeks on 8 GPUs to train).
 - “Residual learning” allows better performance with deep networks:
 - **Include input to layer** in addition to non-linear transform.

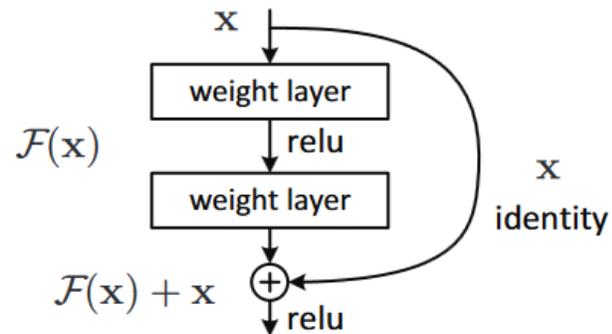


Figure 2. Residual learning: a building block.

- Network just focuses on “residual”: what is not captured in original signal.
- Along with VGG, this is another of the most popular architectures.

DenseNet

- More recent variation is “DenseNets”:
 - Each layer gets to see all the values in the previous layers.
 - Gets rid of vanishing gradients.

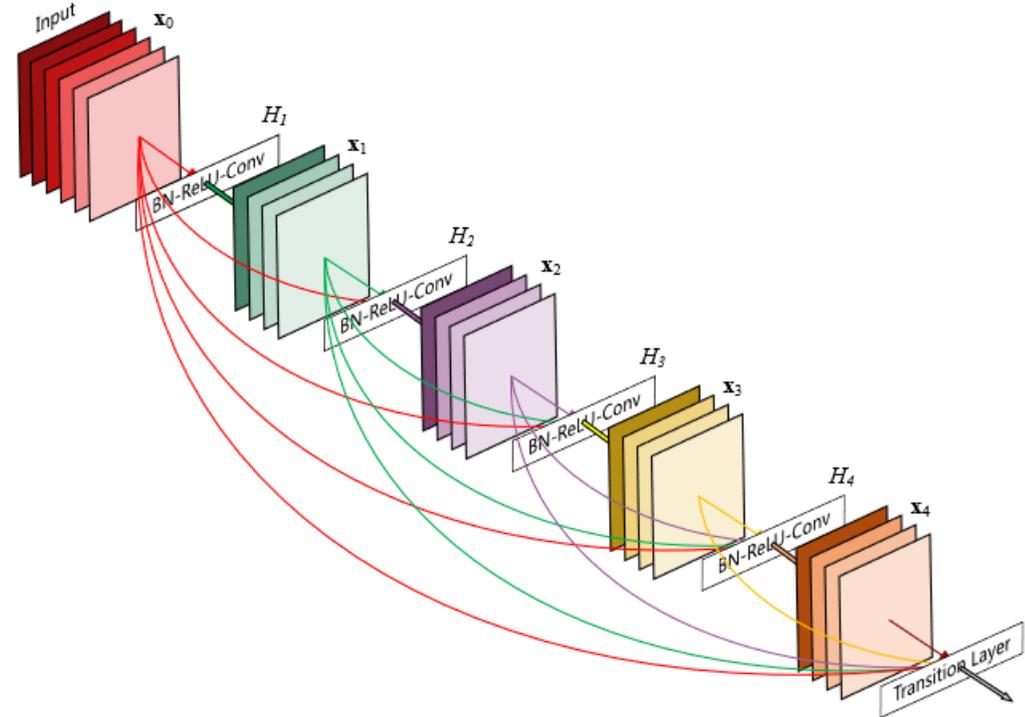
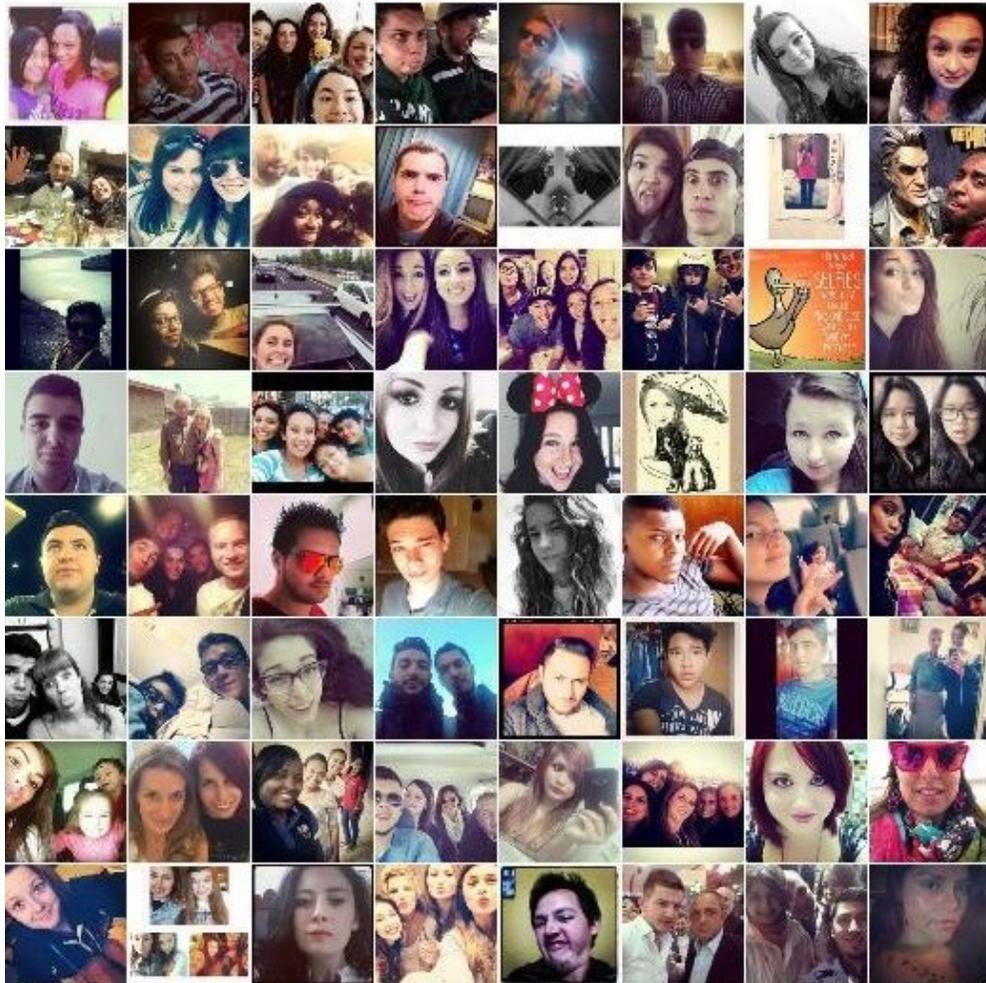


Figure 1: A 5-layer dense block with a growth rate of $k = 4$. Each layer takes all preceding feature-maps as input.

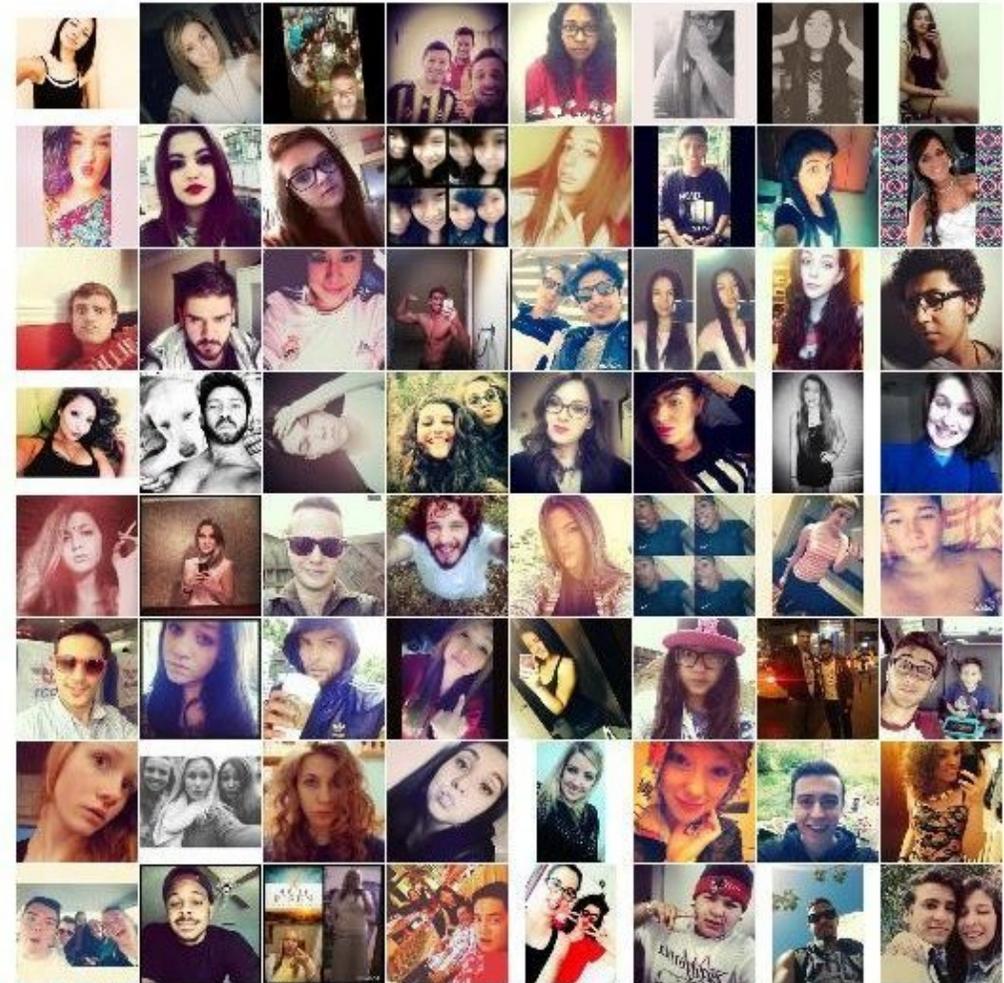
CNNs for Rating Selfies

Our training data

Bad selfies



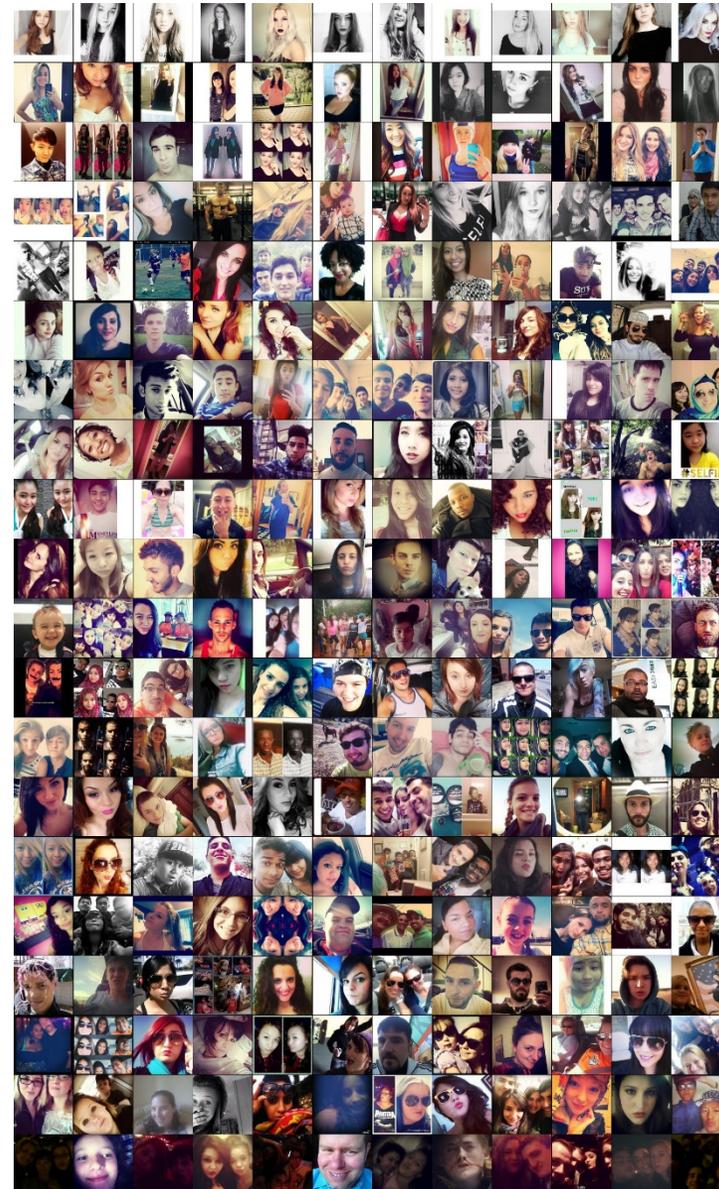
Good selfies



CNNs for Rating Selfies

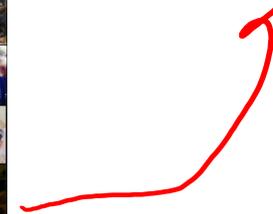
Do: ↙

- Be female
- Have face be $\frac{1}{3}$ of image
- Cut off forehead
- Show long hair
- Oversaturate face
- Use filter
- Add border



Don't:

- Use low lighting
- Make head too big
- Take group shots



CNNs for Rating Selfies

Finding best
image crop:

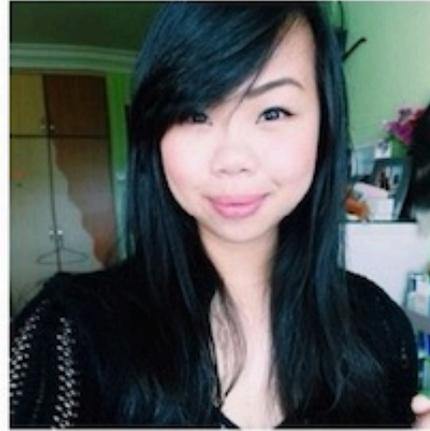
score 66.5



score 69.6



score 53.1



score 67.3



score 44.5



score 62.8



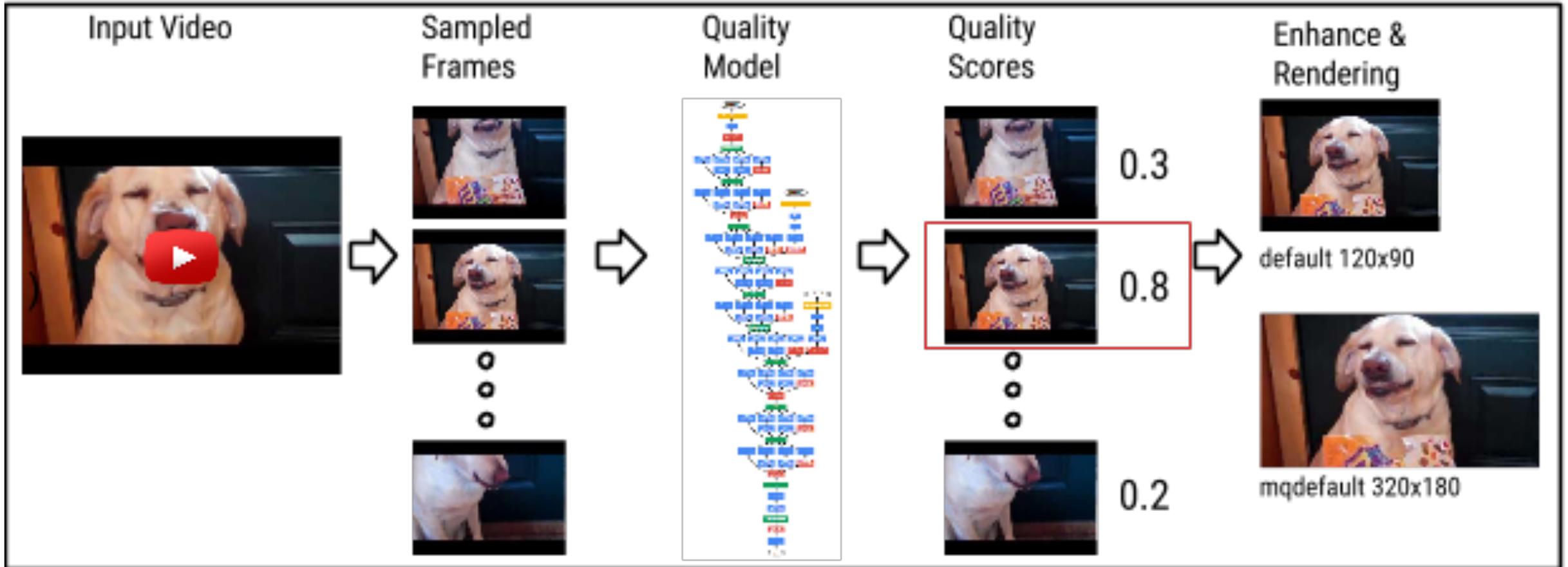
score 52.0



score 56.3



CNNs for Choosing YouTube Thumbnails



Artistic Style Transfer

- Artistic style transfer:
 - Given a content image 'C' and a style image 'S'.
 - Make a image that has content of 'C' and style of 'S'.
- CNN-based approach applies gradient descent with 2 terms:
 - Loss function: match deep latent representation of content image 'C':
 - Difference between $z_i^{(m)}$ for deepest 'm' between x_i and 'C'.
 - Regularizer: match all latent representation covariances of style image 'S'.
 - Difference between covariance of $z_i^{(m)}$ for all 'm' between x_i and 'S'.