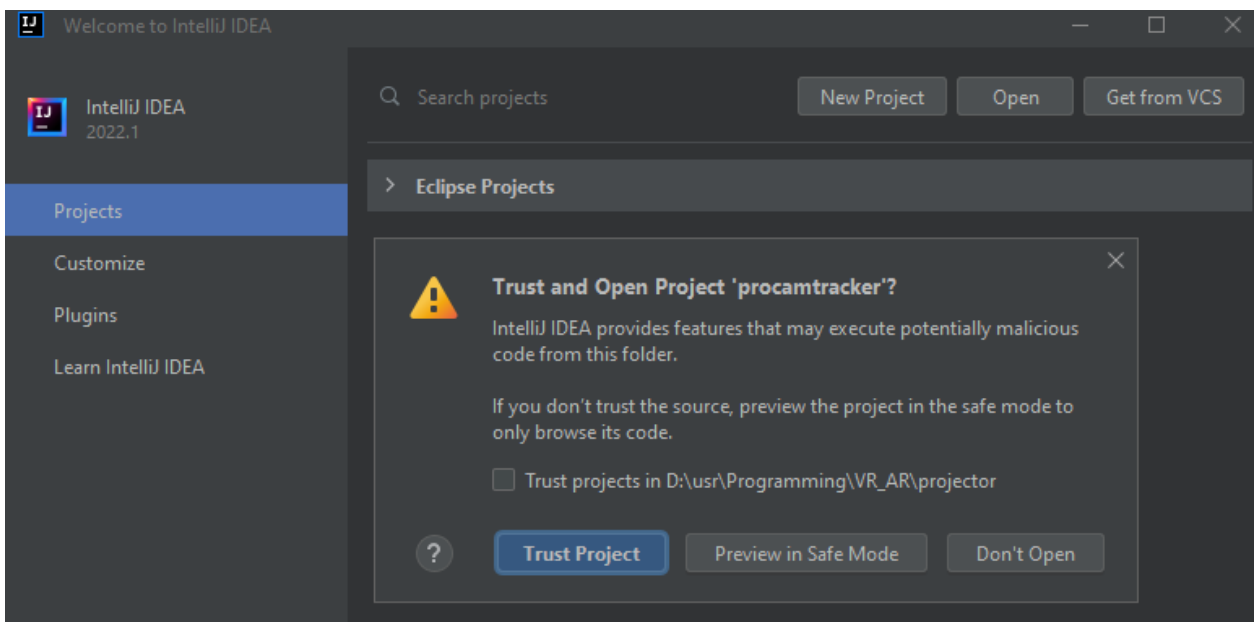
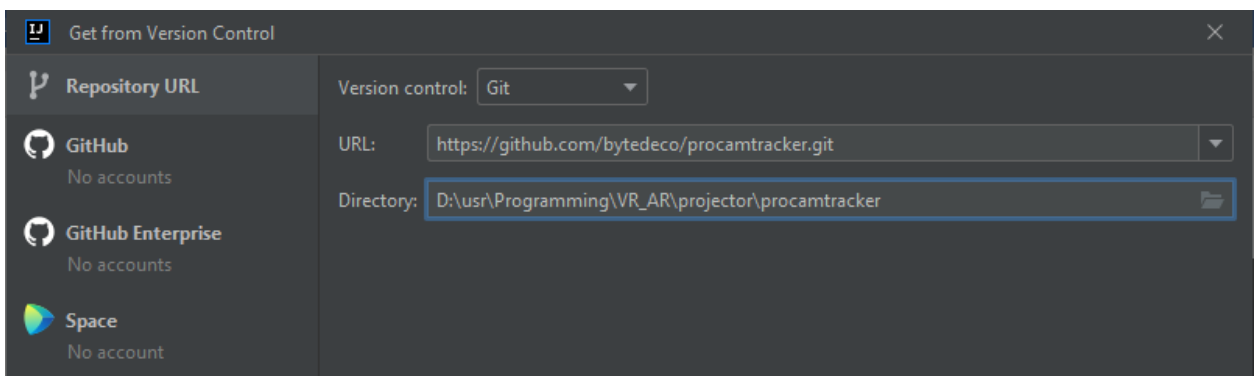
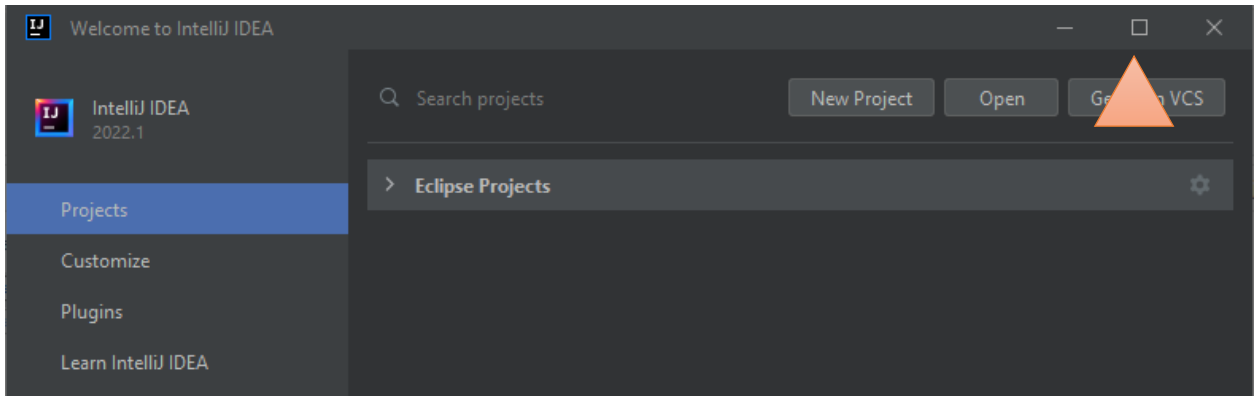


Step 1. Checkout procamtracker



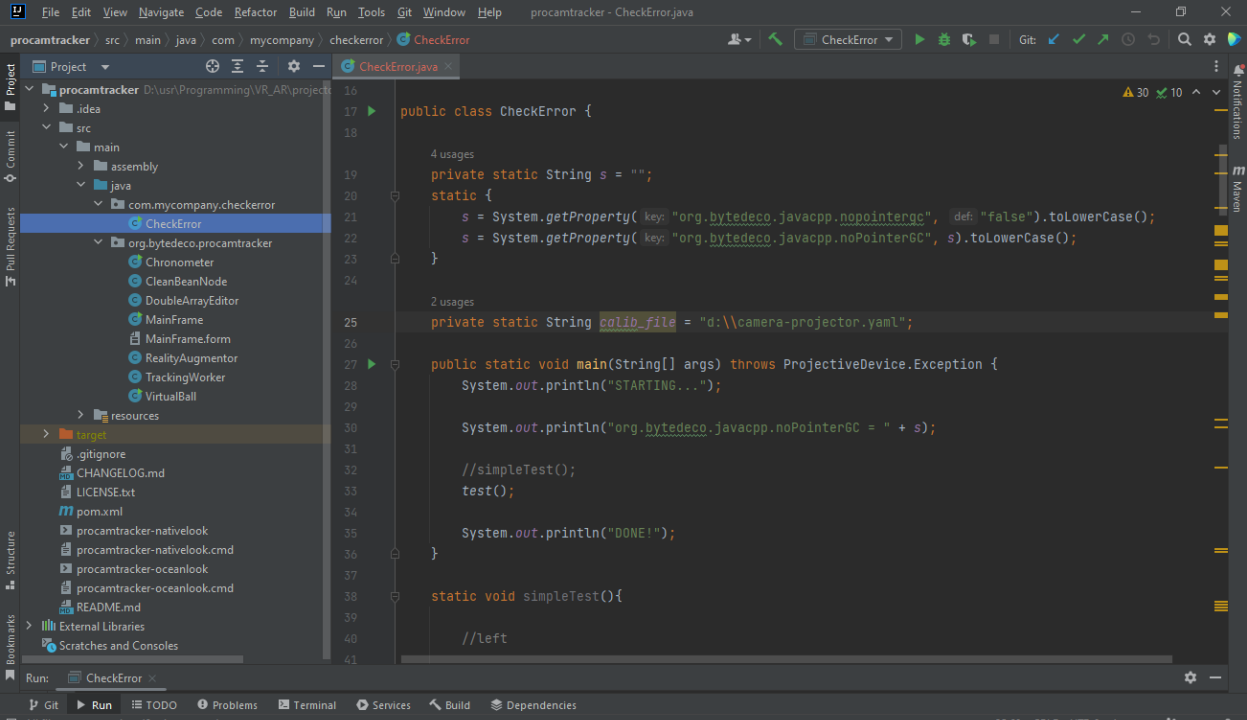
Step 2. Check java version

Java -version

```
java version "13.0.2" 2020-01-14
Java(TM) SE Runtime Environment (build 13.0.2+8)
```

Java HotSpot(TM) 64-Bit Server VM (build 13.0.2+8, mixed mode, sharing)

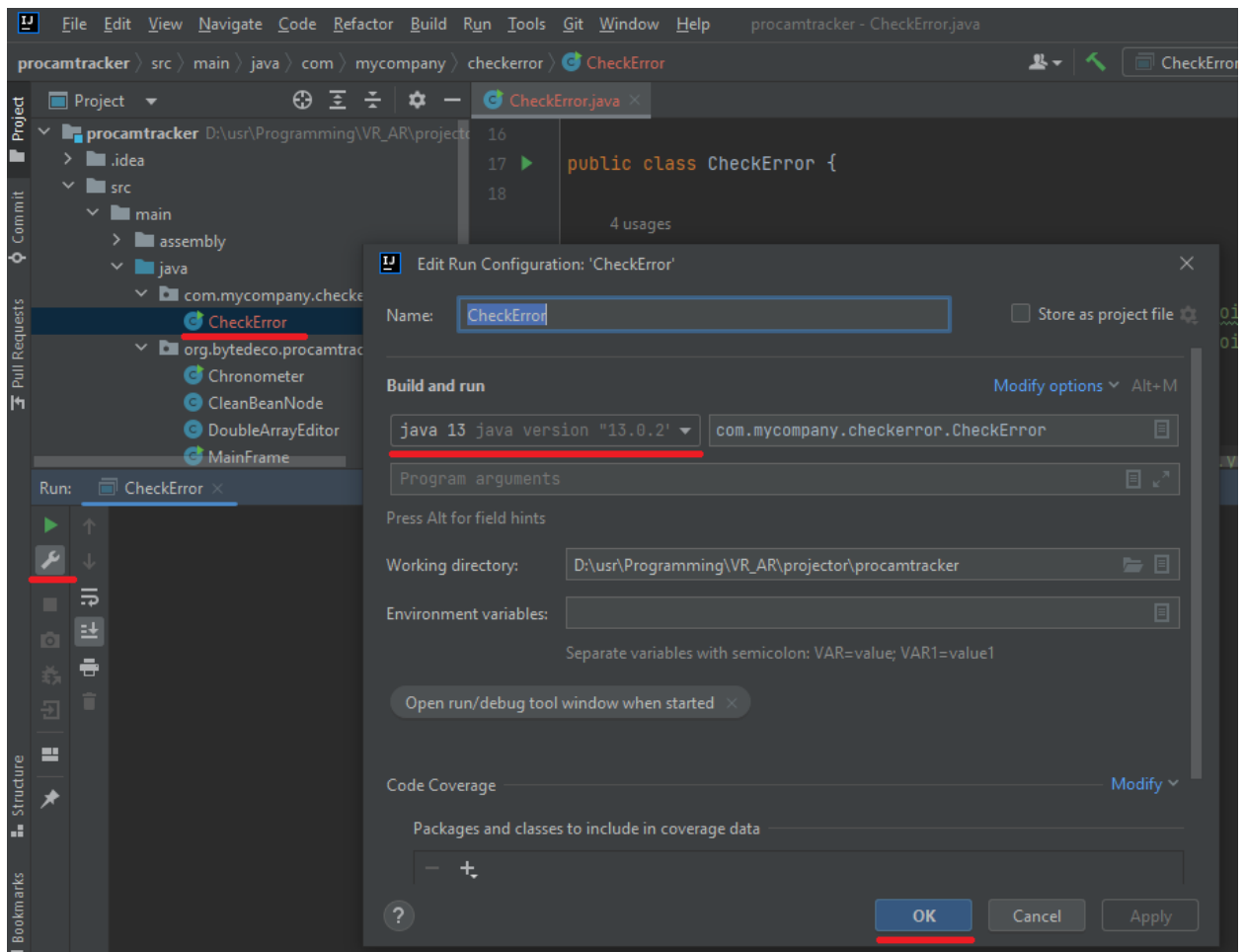
Step 3. Create new Java Class



```
16
17 public class CheckError {
18
19     4 usages
20     private static String s = "";
21     static {
22         s = System.getProperty( key: "org.bytedeco.javacpp.noPointerGC", def: "false").toLowerCase();
23         s = System.getProperty( key: "org.bytedeco.javacpp.noPointerGC", s).toLowerCase();
24     }
25
26     2 usages
27     private static String colib_file = "d:\\camera-projector.yaml";
28
29     public static void main(String[] args) throws ProjectiveDevice.Exception {
30         System.out.println("STARTING...");
31
32         System.out.println("org.bytedeco.javacpp.noPointerGC = " + s);
33
34         //simpleTest();
35         test();
36
37         System.out.println("DONE!");
38     }
39
40     static void simpleTest(){
41
42         //left
43     }
44 }
```

Source code attached

Step 4. Check run configuration



Step 5. Download calibration file and place in D:

Link: <https://github.com/natar-io/PapARt/blob/1.4-github/papart/data/calibration/camera-projector.yaml>

Step 6. Run

```
STARTING...
org.bytedeco.javacpp.noPointerGC = false
Mat K1 = new Mat(3, 3, 6);
K1.put(0, 0, new double[]{
    725.3432277010294,    0.0,    331.91235060120476,
    0.0,    728.0987748056441,    202.35866017353592,
    0.0,    0.0,    1.0
});
Mat K2 = new Mat(3, 3, 6);
K2.put(0, 0, new double[]{
    1940.4781847943073,    0.0,    705.2767131913546,
    0.0,    1746.0863675456435,    761.9744425794147,
    0.0,    0.0,    1.0
});
Mat distCoeff1 = new Mat(1, 4, 6);
distCoeff1.put(0, 0, new double[]{
    0.013108245708010578,    -0.09888522377388584,    -0.010077014999011482,
    7.506298741617942E-4
});
```

```

Mat distCoeff2 = new Mat(1, 4, 6);
distCoeff2.put(0, 0, new double[]{
    0.0610552152371495,    -0.16205979414801663,    -0.0028666292947557306,
    0.001669682933892569
});
Mat R = new Mat(3, 3, 6);
R.put(0, 0, new double[]{
    0.998994700701929,    0.04283205403325078,    0.01322887435710044,
    -0.03679788980716183,    0.9520563182488666,    -0.303701633496023,
    -0.02560279819088608,    0.30290952779618113,    0.952675345904937
});
Mat T = new Mat(3, 1, 6);
T.put(0, 0, new double[]{
    -72.9761951228808,
    -2.1459919519516935,
    -47.133400408948305
});
Size imageSize = new Size(1003,624);

```

```

java.lang.RuntimeException: OpenCV(4.5.5) D:\a\javacpp-presets\javacpp-
presets\opencv\cppbuild\windows-x86_64\opencv-
4.5.5\modules\calib3d\src\undistort.dispatch.cpp:416: error: (-215:Assertion
failed) CV_IS_MAT(_distCoeffs) && (_distCoeffs->rows == 1 || _distCoeffs-
>cols == 1) && (_distCoeffs->rows*_distCoeffs->cols == 4 || _distCoeffs-
>rows*_distCoeffs->cols == 5 || _distCoeffs->rows*_distCoeffs->cols == 8 ||
_distCoeffs->rows*_distCoeffs->cols == 12 || _distCoeffs->rows*_distCoeffs-
>cols == 14) in function 'cvUndistortPointsInternal'

```

```

    at org.bytedeco.opencv.global.opencv_calib3d.stereoRectify(Native
Method)

```

```

    at com.mycompany.checkerror.CheckError.test(CheckError.java:190)

```

```

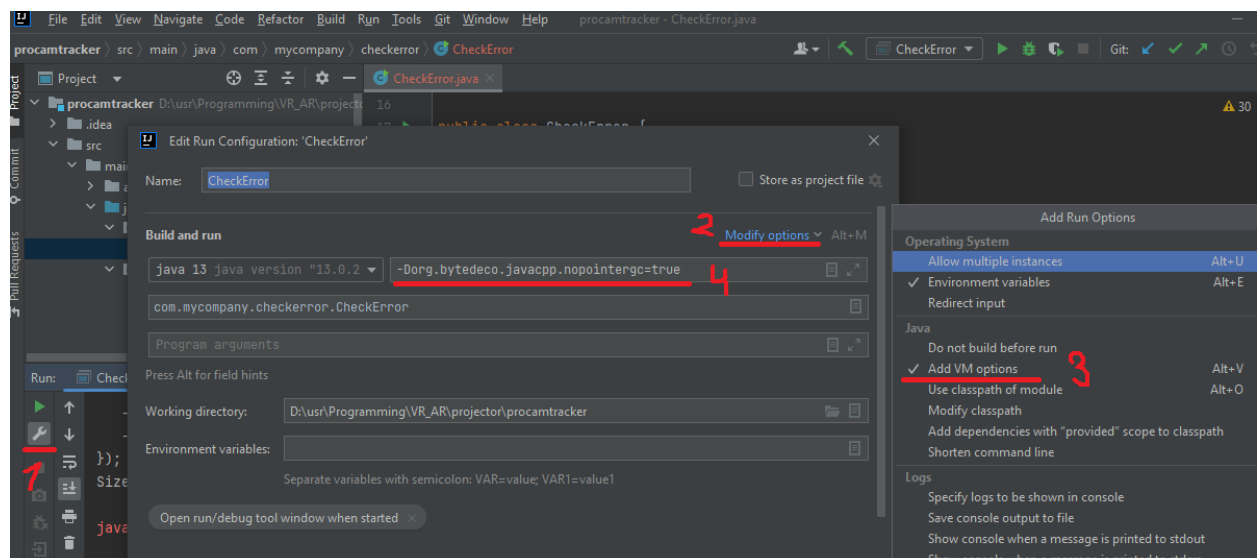
    at com.mycompany.checkerror.CheckError.main(CheckError.java:33)

```

DONE!

Process finished with exit code 0

Step 7. Disabling automatic garbage collection for pointers



Step 8. Run

STARTING...

```
org.bytedeco.javacpp.noPointerGC = true
```

...

Same result with Exception