

```
<launch>
  <env name="GAZEBO_MODEL_PATH" value="$(find fetch_gazebo)/models:$(optenv
GAZEBO_MODEL_PATH)" />

  <arg name="debug" default="false"/>
  <arg name="gui" default="true"/>
  <arg name="headless" default="false"/>

  ##### Start Gazebo with a blank world #####
  <include file="$(find gazebo_ros)/launch/empty_world.launch">
    <arg name="world_name" value="$(find fetch_gazebo)/worlds/cube.sdf"/>
    <arg name="debug" value="$(arg debug)" />
    <arg name="gui" value="$(arg gui)" />
    <arg name="paused" value="false"/>
    <arg name="use_sim_time" value="true"/>
    <arg name="headless" value="$(arg headless)"/>
  </include>

  <include file="$(find fetch_gazebo)/launch/test.launch" />

</launch>
```